MATHEMATICAL THEORY OF PATTERN RECOGNITION

Discriminative Power for Ensembles of Linear Decision Rules¹

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Abstract—A novel class of ensembles of linear decision rules is introduced which includes majority votingbased ensembles as a particular case. Based on this general framework, new results are given that state the ability of a subclass to discriminate between two infinite subsets A and B in \mathbb{R}^n , thus generalizing Mazurov's theorem for two finite sets.

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INTRODUCTION

The conventional formulation of the problem of machine learning for a class of majority voting-based decision rules [1] given samples *A* and *B* in \mathbb{R}^n from two classes is to find a positive integer *k*, vectors $d_i \in \mathbb{R}^n$, thresholds $\alpha_i \in \mathbb{R}$, and weights $w = [w_i]_{i=1}^k \in \mathbb{R}^k_+$ such that, for a decision rule of the form

$$f(\cdot) = H\left[\sum_{i=1}^{k} w_i H((d_i, \cdot) - \alpha_i) - \frac{1}{2} \sum_{i=1}^{k} w_i\right]$$
(1.1)

for any $a \in A$ the condition f(a) = 1 is fulfilled (correspondingly, for any $b \in B$, the condition f(b) = 0 is fulfilled), where

$$H(x) = \begin{cases} 1, & x > 0, \\ 1/2, & x = 0, \\ 0, & x < 0 \end{cases}$$
(1.2)

is the Heaviside function and (\cdot, \cdot) denotes the scalar product in \mathbb{R}^n . Then decision rule (1.1) is called *correct* over sets A and B. It is easy to see that rule f gives 1 for vector $x \in \mathbb{R}^n$ if

$$\sum_{i: H(l_i(x)) = 1} w_i > \sum_{i: H(l_i(x)) = 0} w_i$$
(1.3)

and yields 0 when the reverse strict inequality holds, where $l_i(\cdot) = (d_i, \cdot) - \alpha_i, i = 1, ..., k$.

The notion of separating committee of hyperplanes (linear functions) is closely related to correct decision rules (1.1).

Definition 1.1 [1]. A set $K = \{(l_i, w_i)\}_{i=1}^k$, of pairs is called a *committee* of linear functions which discriminates between (separates) two subsets A and B of R^n if inequalities

$$\sum_{i: l_i(x) > 0} w_i > q/2, \quad \forall x \in A,$$

$$\sum_{i: l_i(x) < 0} w_i > q/2, \quad \forall x \in B$$
(1.4)

are satisfied where $w_i \in Z_+$, $i = 1, ..., k, q = \sum_{i=1}^{k} w_i, Z_+$

denotes a set of positive integers. In addition, q is called the *number of elements* of set K. Functions l_i of the committee are called *elements* of K, whereas w_i are called the *weights* (or *multiplicities*) of these elements.

The separating committee concept represents a simple generalization for a hyperplane that discriminates between two subsets. Furthermore, a committee $K = \{(l_i, w_i)\}_{i=1}^k$ of linear functions corresponds to a specific correct decision rule (1.1) such that the following inequalities hold true:

$$\sum_{i: H(l_i(x)) = 1} w_i > q/2, \quad \forall x \in A,$$

$$\sum_{i: H(l_i(x)) = 0} w_i > q/2, \quad \forall x \in B.$$
(1.5)

It is obvious that (1.5) is stronger than the correctness condition.

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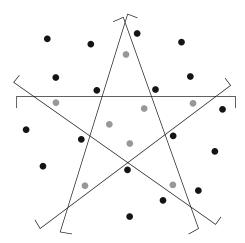


Figure. (4,3,5)—committee of five functions which discriminates between gray and black points. Its functions are depicted by their level sets l(x) > 0. At every gray point at least four functions are positive, whereas for each black point at most three functions are nonnegative.

Theorem 1.1 [1]. A committee exists that separates two finite subsets A and B of \mathbb{R}^n iff $A \cap B = \emptyset$ where its number of elements does not exceed $|A \cup B|$.

Corollary [2]. The VC dimension for class of decision rules (1.1) is infinite.

It is also shown [2] that if $k \le k_0$, then the VC dimension is $O(k_0n)$, where k_0 denotes some fixed positive integer.

The following problem is investigated.

Problem. What are the conditions for possibly infinite subsets A and B of R^n under which a committee exists which discriminates between them?

Theorem 1.2 [3]. A committee exists separating two closed subsets A and B of \mathbb{R}^n iff $A \cap B = \emptyset$ and at least one of these subsets has a finite upper bound; as well one of the two has a finite lower bound.

Below, a separating (s, t, q)-committee concept is introduced (Def. 2.1), which covers separating committee notion (Def. 1.1) as a special case. Based on it a new technique is applied to give proofs for sufficient conditions under which two closed subsets A and B of R^n with $A \cap B = \emptyset$ are separable by a committee.

DEFINITION OF SEPARATING (s, t, q)-COMMITTEE

Let *A* and *B* be subsets of R^n , *s* and *t* be positive integers with s > t.

Definition 2.1 A set $K = \{(l_i, w_i)\}_{i=1}^k$ of pairs is called an (s, t, q)-committee of linear functions that

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discriminates between two subsets *A* and *B* if the following inequalities hold true:

$$\sum_{i: \ l_i(x) > 0} w_i \ge s, \quad \forall x \in A,$$

$$\sum_{i: \ l_i(x) \ge 0} w_i \le t, \quad \forall x \in B,$$

$$i: \ l_i(x) \ge 0 \quad (2.1)$$

$$\sum_{i: \ l_i(x) \ge 0} w_i \le t, \quad \forall x \in B,$$

where $l_i(\cdot) = (d_i, \cdot) - \alpha_i, d_i \in \mathbb{R}^n, \alpha_i \in \mathbb{R}, w_i \in \mathbb{Z}_+,$ $i = 1, ..., k, q = \sum_{i=1}^k w_i.$

An example of a (4,3,5)-committee is shown in the figure. Obviously, the (s, t, q)-committee defines some piecewise-linear surface which separates subsets A and B. It also corresponds to a decision rule of the form

$$f(\cdot) = H\left[\sum_{i=1}^{k} w_i H(l_i(\cdot)) - \frac{s+t}{2}\right],$$
 (2.2)

which is correct over sets *A* and *B*. It is easy to show that the (q, q - 1, q)-committee outlines the surface of a convex polyhedron *M* containing set *A* inside and set *B* outside $R^{n/M}$. Furthermore, we obviously find that the (s, t, q)-committee becomes a committee for s > q/2 > t.

Suppose that set *A* can be separated by a (t + 1, t, q)-committee from set *B*. Conversely, if *B* is separable from *A* by a surface of the same shape, then a (q - t, q - 1 - t, q)-committee exists that separates *A* and *B*.

The notions of a committee and the (s, t, q)-committee are closely related. Consider a set $K = \{(l_i, w_i)\}_{i=1}^k$ of pairs. Let us find out what the conditions are under which this set can be augmented to some committee that separates A and B by adding one of two functions $l_T(\cdot) \equiv (0, \cdot) + 1$ or $l_F(\cdot) \equiv (0, \cdot) - 1$ with some weight where 0 denotes zero vector in \mathbb{R}^n .

Theorem 2.1. The set of pairs $K = \{(l_i, w_i)\}_{i=1}^k$ can be transformed to a committee that discriminates between sets A and B in \mathbb{R}^n by adding one of two functions $l_T(\cdot) \equiv (0, \cdot) + 1$ or $l_F(\cdot) \equiv (0, \cdot) - 1$ iff K is a (s, t, q)committee that separates A and B for some positive integers s and t with s > t.

Proof. In the case when set *K* transforms to a committee \overline{K} by adding pair (l_T, w_{k+1}) , we have the following inequalities according to Def. 1.1:

$$\sum_{\substack{i \neq k+1, l_i(x) > 0 \\ k \neq k+1, l_i(x) < 0}} w_i + w_{k+1} > p/2, \quad x \in A,$$
(2.3)

where $p = \sum_{i=1}^{k+1} w_i$. It can be assumed that p is odd

(a committee whose number of elements is even can be reduced to a committee by decrementing weight w_i of one of its functions l_i). Set $s = \lceil p/2 \rceil - w_{k+1}$ and $t = \lfloor p/2 \rfloor - w_{k+1}$, where $\lfloor x \rfloor$ and $\lceil x \rceil$ denote rounding to the closest integer, which is less than or more than real x, respectively. In view of $w_i \in Z_+$ for every i = 1, ..., k + 1 and keeping in mind that p is odd, we obtain

$$\sum_{\substack{i \neq k+1, l_i(x) > 0}} w_i \ge s, \quad x \in A,$$

$$\sum_{\substack{i \neq k+1, l_i(x) \ge 0}} w_i \le t, \quad x \in B.$$
(2.4)

If *K* transforms to a committee \overline{K} by adding pair (l_F, w_{k+1}) , the same path can be followed by setting $s = \lceil p/2 \rceil$ and $t = \lfloor p/2 \rfloor$.

Conversely, let
$$q = \sum_{i=1}^{k} w_i$$
. When $t < q/2 < s$, set K is

a committee that separates *A* and *B*. Therefore, adding any two functions l_T or l_F with $w_{k+1} = 0$ gives the committee \overline{K} . Now assume that $q/2 \notin (t, s)$. Consider the case q = 2h for some positive integer *h*. If $t \ge h$, we add the function l_F to *K* with $w_{k+1} = 2(t-h) + 1$. For the set \overline{K} thus obtained we have $\sum_{i=1}^{k+1} w_i = 2t + 1$. In view of

s > t and the inequalities

$$\sum_{i: l_i(x) > 0} w_i \ge s \ge t+1, \quad x \in A,$$

$$\sum_{i: l_i(x) \ge 0} w_i \le t, \quad x \in B$$
(2.5)

we find that \overline{K} is a committee. However, if h > t then $h \ge s$. In this case let us add function l_T to K with $w_{k+1} = 2(h-s) + 1$. For the resulting set of pairs we have $\sum_{i=1}^{k+1} w_i = 2(2h-s) + 1$ and $\sum_{i:l_i(x)>0} w_i \ge s + 2(h-s) + 1 = 2h-s+1, \quad x \in A,$

(2.6)
$$\sum_{i: \ l_i(x) \ge 0} w_i \le t + 2(h-s) + 1 \le 2h-s, \quad x \in B,$$

where summation is performed over all *i* from 1 to k + 1.

Now consider the case q = 2h - 1. When h > s, we add function l_T to K with $w_{k+1} = 2(h - s)$. For the set of pairs thus augmented we find that $\sum_{i=1}^{k+1} w_i = 2(2h - s) - 1$ and

$$\sum_{i: l_i(x) > 0} w_i \ge s + 2(h - s) = 2h - s, \quad x \in A,$$
(2.7)
$$\sum_{i: l_i(x) > 0} w_i \le t + 2(h - s) \le 2h - s - 1, \quad x \in B.$$

$$\sum_{i:\ l_i(x) \ge 0} w_i \le t + 2(h-s) \le 2h-s-1, \quad x \in B.$$

In the case $h \le s$, the inequality $h \le t$ holds. Let us add function l_F to K with $w_{k+1} = 2(t-h+1)$ and follow the k+1

same path. We have
$$\sum_{i=1}^{n} w_i = 2t + 1$$
 and
 $\sum_{i: \ l_i(x) > 0} w_i \ge s \ge t + 1, \quad x \in A,$
(2.8)

$$\sum_{i: l_i(x) \ge 0} w_i \le t, \quad x \in B.$$

The theorem is proved.

SUFFICIENT CONDITIONS FOR EXISTENCE OF A COMMITTEE THAT DISCRIMINATES BETWEEN TWO INFINITE SUBSETS OF *R*ⁿ

Let us introduce some auxiliary constructions and notations. At first we describe union operation for two finite sets of pairs. Let *K* and *L* be two finite sets of pairs whose elements (first components of pairs, see Def. 1.1) belong to an arbitrary set *X*. Let us define the set of pairs *K*' in the following way. Each element of *K* but not of *L* is added to *K*' with the weight this element has for set *K*. Analogously, each element of *L* not belonging to *K* is added to *K*' with the same multiplicity as the one for *L*. Finally, each element which belongs to both *K* and *L* with weights p_1 and p_2 , respectively, is included in *K*' with multiplicity $p_1 + p_2$. Denote $K \cup L =: K'$. For three sets K_1, K_2 , and K_3 set $K_1 \cup K_2 \cup K_3 := (K_1 \cup K_2) \cup K_3$. The union of four and more sets is defined in the same way.

In the sequel int *M* denotes the interior of set *M*, whereas set cl *M* gives closure of *M* and bd *M* is its border. For simplicity we identify linear function *l* with its level set (half-space) $P = \{x \in \mathbb{R}^n : l(x) > 0\}$, whereas separating committee of linear functions is the same as the set of pairs of the form (half-space, its weight). If $l(x) \equiv \alpha \in \mathbb{R}$, the corresponding half-space *P* is the empty set for $\alpha \leq 0$ and coincides with the whole space for $\alpha > 0$. Also we say that open half-space *P* votes for point $a \in A$ if $a \in P$ and votes for $b \in B$ if $b \notin cl P$. If $P = \emptyset$, then *P* votes for each point of *B* (for set *B*) and against set *A*. In the opposite case, $P = R^n$ halfspace *P* votes for set *A* and against set *B*. It is easy to see that set of pairs $\{(l_i, w_i)\}_{i=1}^k$ is a committee that separates *A* and *B* iff for each point of $A \cup B$ a majority of half-spaces votes for in the corresponding set of pairs $\{(P_i, w_i)\}_{i=1}^k$, where $P_i = \{x \in R^n: l_i(x) > 0\}, i = 1, ..., k$.

The following theorem generalizes theorem 1.1 in the case of infinite sets *A* and *B*.

Theorem 3.1. If A and B are closed subsets of \mathbb{R}^n with $A \cap B = \emptyset$ such that one of them is bounded and has finite number of limiting points, then a committee exists that separates A and B.

Proof. Let *A* and *B* be two closed subsets of \mathbb{R}^n with $A \cap B = \emptyset$ such that *A* is bounded set having finite number of limiting points. It is easy to see that *A* is countable or finite. As *A* and *B* are closed sets, *A* is bounded and $A \cap B = \emptyset$, there exists such $\rho > 0$ that any ball of radius ρ centered at arbitrary point of *A* does not contain points of *B*.

Let us give the following procedure. Let A' be an arbitrary finite subset of A and $a \in A'$ be some vertex of the convex hull convA'. Consider an arbitrary *n*-dimensional simplex S containing convex hull convA' which has point a as one of its vertices. Get the (n - 1)-dimensional face of S which is opposite to a and consider hyperplane H parallel to that face which cuts off an *n*-dimensional simplex from S that is contained in the ball centered at a of radius ρ .

Simplex *S* is the intersection of some set of n + 1 closed half-spaces. Let *P* be the half-space containing point *a* and whose border is hyperplane *H*. Let us shift each of these n + 1 half-spaces bounding *S* in parallel and denote by *T* the simplex thus obtained. We perform shifting in such a way that $S \subset \text{int } T$ and $A \cap$ bd $T = \emptyset$. This last condition holds because *A* is countable or finite. Moreover, we shift the half-space *P* in parallel in such a way that the border of the shifted half-space starts to nip some *n*-dimensional simplex T_1 from simplex *T* with $a \in \text{int } T_1$ and $T_1 \cap B = \emptyset$.

Simplices T_1 and T have a common vertex, which we denote by c_1 . Let $c_2, ..., c_{n+1}$ be the other vertices of T. For each s = 2, ..., n + 1 consider the cone K_s bounded by n different hyperplanes each of which passes through some (n - 1)-dimensional face of Tcontaining point c_s with $K_s \cap T = \{c_s\}$. Get the (n - 1)dimensional face of T opposite to c_s . Using a hyperplane parallel to that face, cut off some simplex T_s from simplex T such that $T_s \cap A = \emptyset$. Such a construction is possible in view of $c_s \notin A$. The procedure is finished.

This procedure is used for set A' from which elements are deleted consecutively. In three stages we get a committee that separates A and B.

STAGE 1. Let A_0 be the set of limiting points of bounded set A which is finite due to the theorem. Set

 $t_0 = |A_0|$ and $A' = A_0$. Consider a system of simplices T, $T_1, ..., T_{n+1}$ provided by the procedure applied for set A' and for an arbitrary vertex a_1 of convex hull convA'. Let $V^1 := T$ and $V_s^1 := T_s, s = 1, ..., n + 1$. Setting A' := $A' \setminus \{a_1\}$ we apply the procedure for set A' and for an arbitrary vertex a_2 of convex hull convA'. As a result we have another system $T, T_1, ..., T_{n+1}$ of simplices. Let $V^2 := T$ and $V_s^2 := T_s, s = 1, ..., n + 1$ set $A' := A' \setminus \{a_2\}$. We continue repeating the procedure until set A'becomes empty. Obviously, sequence $a_1, ..., a_{t_0}$ thus obtained coincides with set A_0 . For each $r = 1, ..., t_0$ consider an open neighborhood $U(a_r)$ of point a_r which is contained in $V_1^r \cap \bigcap_{i=1}^{r-1} V^i$ as a subset. Due to

the boundedness of A, the set $A_1 = A \setminus \bigcup_{r=1}^{t_0} U(a_r)$ is

finite.

In the case $A_0 = \emptyset$, we set $A' := A_1 = A$ and p := 1going to stage 2. Otherwise, for $A_0 \neq \emptyset$ we apply the following simplex generation process. Set p := 1 and $A' = A_1 \cup ver V^1$, where $ver V^1$ is the vertex set for simplex V^1 . When convex hull convA' does not coincide with V^1 , some point $a \in A_1$ will be a vertex of the hull. Obtain simplices $T, T_1, ..., T_{n+1}$ applying the procedure for the set A' and the point a. Set $a'_1 := a$, $T^1 :=$ $T, T_s^1 := T_s$, where s = 1, ..., n + 1. Then set A' := $A' \setminus \{a\}$ and p := 2. If the convex hull convA' still does not equal to the simplex V^1 consider an arbitrary point $a \in A_1$ being a vertex of the hull. By applying the procedure for the set A' and the point a we get another simplex series $T, T_1, ..., T_{n+1}$. Again set $a'_2 := a, T^2 :=$ $T, T_s^2 := T_s, s = 1, ..., n + 1$. Let $A' := A' \setminus \{a\}$ and p := 3. While $\operatorname{conv} A' \neq V^1$ we continue going in the same way.

Due to the fact that $A_1 \setminus V^1$ is finite, we finally arrive at the case conv $A' = V^1$ for some $p = p_1$. Set $a'_{p_1} := a_1$, $T^{p_1} := V^1$, $T^{p_1}_s := V^1_s$, where s = 1, ..., n + 1. Let $p := p_1 + 1$. We now follow the same way of simplex generation for r = 2. Specifically, let $A' := (A' \setminus ver V^{r-1}) \cup ver V^r$. If the convex hull conv A' does not coincide with V^r , let us get a vertex a of the hull that is contained in A_1 . By applying the procedure for set A' and point a, we obtain a system $T, T_1, ..., T_{n+1}$ of simplices. Then we set $a'_p := a, T^p := T, T^p_s := T_s, s = 1, ..., n + 1$ and let $A' := A' \setminus \{a\}$ and p := p + 1. While conv $A' \neq V^r$ we continue repeating this process. Again we come to the case where conv $A' = V^r$ for some $p = p_r$. Then let $a'_{p_r} := a_r$,

$$T^{p_r} := V^r, \ T^{p_r}_s := V^r_s, \ s = 1, \dots, n+1 \text{ and set } p := p_{r+1}.$$

The whole process works for $r = 3, 4, ..., t_0$. At the end we delete from A' all vertices of simplex V^{t_0} . It is easy to see that $A' = A_1 \cap \bigcap_{i=1}^{t_0} V^r$.

STAGE 2. In the case $A' \neq \emptyset$ we apply the procedure for set A' and for an arbitrary vertex of its convex hull. Having provided the system of simplices T, $T_1, ..., T_{n+1}$, we set $a'_p := a$, $T^p := T$, $T^p_s := T_s$, s = 1, ..., n+1. Also let $A' := A' \setminus \{a\}$ and p := p+1. Finally, while set A' is nonempty we continue doing the same.

STAGE 3. At the end of stage 2, we have two families {*T^k*} and {*T^k*_s} of simplices where *s* = 1, ..., *n* + 1 and *k* = 1, ..., *t*, *t* = |*A*₀| + |*A*₁|. For each *k*, 1 ≤ *k* ≤ *t*, define a series of open half-spaces {*P^k*_{*i*}}^{2*n*+2}_{*i*=1} by the conditions int $T^k = \bigcap_{i=1}^{n+1} P^k_i$ int $T^k_1 = \bigcap_{i=2}^{n+2} P^k_i$ and int $T^k_s = Q^k_{n+1+s} \cap \bigcap_{i=1, i \neq s}^{n+1} Q^k_i$, where $2 \le s \le n+1$ and Q^k_i is the open half-space distinct from P^k_i , which has a common boundary with P^k_i . Equip set L_k of pairs with these half-spaces taken with some multiplicities. Each of the half-spaces { P^k_i }^{*n+1*}_{*i*=1} will have weight $n \cdot n^{2(t-k)}$, whereas each of the half-spaces { P^k_i }^{*i*=*n*+2}, the weight $n^{2(t-k)}$. Let $K_0 = \{(P_0, w_0)\}$, where $P_0 = \{x \in R^n: (0, x) > 1\}$ and $w_0 = n^{2t}$. Set $K = K_0 \cup L_1 \cup ... \cup L_t$, where symbol \cup denotes union operation. Stage 3 is finished.

Let us show that *K* is a committee. Consider the case where $n \neq 1$. Since the number of elements for the set L_k is equal to $(n + 1)^2 n^{2(t-k)}$, k = 1, ..., t, the number of elements for *K* is equal to

$$(n+1)^{2}(n^{2(t-1)}+n^{2(t-2)}+\ldots+1)+n^{2t}$$

= $2n^{2t}-1+\frac{2}{n-1}(n^{2t}-1).$ (3.1)

Let us count the number of elements of L_k , k = 1, ..., twhich vote for some $a \in A$. Due to the procedure, two situations are possible for each point $a \in A$: a is in the interior of simplex T^k ; otherwise it lies in its open exterior. If $a \in \text{int } T^k$, the half-spaces $\{P_i^k\}_{i=1}^{n+1}$ vote for point a by their multiplicities $n \cdot n^{2(t-k)}$, totaling $(n+1)n \cdot n^{2(t-k)}$ votes. Moreover, if $a \in \text{int } T_1^k$, halfspace P_{n+2}^k votes for a by its weight $n^{2(t-k)}$ and each of the half-spaces $\{P_i^k\}_{i=1}^{n+1}$, by their multiplicities $n \cdot n^{2(t-k)}$, which amounts to $((n + 1)n + 1)n^{2(t-k)}$ votes. Two cases are possible for $a \notin T^k$. The first case takes place when $a \in P_{i_1}^k \cap P_{i_2}^k$ for some i_1 and i_2 , $1 \le i_1$, $i_2 \le n + 1$. The second case is where $a \in \bigcap_{i=1, i \ne i_0}^{n+1} \operatorname{cl}Q_i^k$, for some $i_0, 1 \le i_0 \le n+1$. If the first case holds, there are at least $2n \cdot n^{2(t-k)}$ votes for point a in set L_k . In the second case, in view of $T_s^k \cap A = \emptyset$ for every s = 2, ..., n + 1 and taking inclusion $P_{n+2}^k \supset \bigcap_{i=2}^{n+1} \operatorname{cl}Q_i^k$ into account, we find that half-space $P_{i_0}^k$ votes for point a a by its weight $n \cdot n^{2(t-k)}$, while halfspace $P_{n+1+i_0}^k$ does the same by its multiplicity $n^{2(t-k)}$, which totals $(n + 1)n^{2(t-k)}$ votes in L_k .

Let us count the number of elements of K which vote for some point $a \in A$. Obviously, the finite sequence $a'_1, ..., a'_t$ of distinct points that forms at stages 1 and 2 coincides with set $A_0 \cup A_1$. In view of equality $A = A_1 \cup \bigcup_{a' \in A_0} (U(a') \cap A)$, we have either a =

 a'_p for some $p, 1 \le p \le t$ or $a \in U(a^0)$, where $a^0 \in A_0$. Let us count the number of votes for the first case. Due to the generation procedure for simplices $\{T^k\}$ and $\{T^k_s\}$, point *a* lies inside the intersection $T^p_1 \cap \bigcap_{1 \le k < p} T^k$. Consequently, for $p \ne 1$ and $p \ne t$, the number of elements

of K which vote for a is greater than or equal to

$$(n+1)n(n^{2(t-1)} + ... + n^{2(t-p+1)}) + ((n+1)n+1)n^{2(t-p)} + (n+1)(n^{2(t-p-1)} + ... + 1) = n^{2t} - n^{2(t-p+1)}$$

$$+\frac{1}{n-1}(n^{2t}-n^{2(t-p+1)})+n^{2(t-p+1)}$$
(3.2)
$$+\frac{1}{n-1}n^{2(t-p+1)}-\frac{1}{n-1}n^{2(t-p)}$$

$$+\frac{1}{n-1}n^{2(t-p)}-\frac{1}{n-1}=n^{2t}+\frac{1}{n-1}(n^{2t}-1).$$

For p = 1, this number is greater than or equal to

$$((n+1)n+1)n^{2(t-1)} + (n+1)(n^{2(t-2)} + \dots + 1)$$

= $n^{2t} + \frac{1}{n-1}(n^{2t} - 1).$ (3.3)

Analogously, for p = t the number is at least as great as

$$(n+1)n(n^{2(t-1)} + \dots + n^{2}) + ((n+1)n+1)$$

= $n^{2t} + \frac{1}{n-1}(n^{2t}-1).$ (3.4)

Now consider the case $a \in U(a^0)$, where a^0 is some point of set A_0 . Since $a^0 = a'_p$ for some $p, 1 \le p \le t$, point a lies inside intersection $T_1^p \cap \bigcap_{1 \le k < p} T^k$ by the construction of neighborhood $U(a^0)$ and series of simplices $\{T^k\}$ and $\{T_s^k\}$. As a consequence, there are at least $n^{2t} + \frac{1}{n-1}(n^{2t}-1)$ votes in K for point a.

For every point $b \in B$, let us now count the number of elements of L_k , k = 1, ..., t, which vote for b. If $b \in T^k$, we have $b \notin T_1^k$ according to the construction of simplex T_1^k . For this point, each of the half-spaces $\{P_i^k\}_{i=n+2}^{2n+2}$ votes by its weight $n^{2(t-k)}$, which overall amounts to $(n + 1)n^{2(t-k)}$ votes. In the case of $b \notin T^k$, some half-space $P_{i_0}^k$, $1 \le i_{0 \le n+1}$, votes for b by its multiplicity $n \cdot n^{2(t-k)}$ and so does half-space $P_{n+1+i_0}^k$ by its weight $n^{2(t-k)}$, whose boundary is parallel to that for $P_{i_0}^k$. It sums up to give at least $(n + 1)n^{2(t-k)}$ votes for b in L_k . Due to the fact that P_0 votes for the B by its multiplicity n^{2t} , the number of elements of K which vote for point b is at least as much as $(n + 1)(n^{2(t-1)} + ... + 1) + n^{2t} = n^{2t} + \frac{1}{n-1}(n^{2t} - 1)$, so K is a committee.

For n = 1 it is easy to count that the number of elements of *K* is equal to 4t + 1, while the number of elements voting for an arbitrary point of $A \cup B$ is greater than or equal to 2t + 1. The theorem is proved.

Remark. Using more general notion of an (s, t, q)committee yields a simpler proof for the case where set A is finite.

The boundedness condition imposed on one of two sets being separated is essential.

Example. There is no committee which separates sets $A = \{2k\}_{k=1}^{\infty}$ and $B = \{2k-1\}_{k=1}^{\infty}$.

In contrast, if such a committee exists, there is a linear function in K having a positive weight that takes positive value for 2k and gives a negative value for 2k - 1, where k is an arbitrary positive integer. Due to the fact that these functions are different for distinct k and using the finiteness of the committee, we find that a committee that separates these two sets does not exist.

Let us give the classical result on the external approximation of solid convex compact by a convex

polyhedron to arbitrary accuracy (see, e.g., [5]). We call

$$\delta(C_1, C_2) = \max[\sup\{\rho(x, C_2) : x \in C_1\}, \\ \sup\{\rho(x, C_1) : x_2 \in C_2\}]$$
(3.5)

the *Hausdorff* metric between two convex compact subsets C_1 and C_2 of \mathbb{R}^n having a nonempty interior (which are called convex bodies), where $\rho(x, C) :=$ $\inf\{|x-y|: y \in C\}$ and $|\cdot|$ denotes the Euclidean norm. For a given convex body C, we consider convex hulls of finite sets with at most m faces (facets having the maximal dimension), which contain set C and touch its boundary where m is given positive integer. We denote

by $P_m^c(C)$ the set of all convex hulls of this form and set

$$\delta(C, P_m^{\mathfrak{c}}(C)) = \inf\{\delta(C, D) \colon D \in P_m^{\mathfrak{c}}(C)\}.$$

Theorem 3.2 [5]. The following equality holds true: $\lim_{m \to \infty} \delta(C, P_m^c(C)) = 0.$

The following theorem is closely related to the classical result on the separability of two convex sets by a hyperplane.

Theorem 3.3. If A and B are closed subsets of \mathbb{R}^n with an empty intersection where A is a convex body, then A and B are separable by a committee.

Proof. Since A is compact, B is closed and $A \cap B = \emptyset$ we have

$$\rho(A, B) := \inf\{|x - y| : x \in A, y \in B\} = \varepsilon_0 > 0. \quad (3.6)$$

Set
$$A(\varepsilon) = \bigcup_{x \in A} O_x(\varepsilon)$$
 is a compact body, where $O_x(\varepsilon)$

is an *n*-dimensional ball centered at point $x \in \mathbb{R}^n$ of radius ε . Set $A_0 = A(\varepsilon_0/4)$. Then $\rho(A_0, B) > \varepsilon_0/2$. Choose a positive integer *m* large enough to have $\delta(A_0, B) = \delta(A_0, B)$.

 $P_m^c(A_0)$ < $\varepsilon_0/4$. Therefore, there exists $M \in P_m^c(A_0)$ such that $A_0 \subseteq M$ and $M \cap B = \emptyset$ so that $A \subseteq \text{int } M$. Because M coincides with the intersection of a finite number (say, $t \le m$) of closed half-spaces, there exists a (t, t - 1, t)-committee that separates A and B. Then, according to theorem 2.1, there exists a committee that separates them. The theorem is proved.

CONCLUSIONS

A new concept of the (s, t, q)-committee decision rule is introduced which includes the committee decision rule as a special case. A series of sufficient conditions for two subsets A and B of R^n is considered under which there exists a correct decision rule where A and B are not finite in general. These results generalize VI.D.Mazurov's famous criterion on the separability of two finite subsets of R^n having an empty intersection.

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