# Discriminative Power for Ensembles of Linear Decision Rules ${ }^{1}$ 

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#### Abstract

A novel class of ensembles of linear decision rules is introduced which includes majority votingbased ensembles as a particular case. Based on this general framework, new results are given that state the ability of a subclass to discriminate between two infinite subsets $A$ and $B$ in $R^{n}$, thus generalizing Mazurov's theorem for two finite sets.


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## INTRODUCTION

The conventional formulation of the problem of machine learning for a class of majority voting-based decision rules [1] given samples $A$ and $B$ in $R^{n}$ from two classes is to find a positive integer $k$, vectors $d_{i} \in R^{n}$, thresholds $\alpha_{i} \in R$, and weights $w=\left[w_{i}\right]_{i=1}^{k} \in R_{+}^{k}$ such that, for a decision rule of the form

$$
\begin{equation*}
f(\cdot)=H\left[\sum_{i=1}^{k} w_{i} H\left(\left(d_{i}, \cdot\right)-\alpha_{i}\right)-\frac{1}{2} \sum_{i=1}^{k} w_{i}\right] \tag{1.1}
\end{equation*}
$$

for any $a \in A$ the condition $f(a)=1$ is fulfilled (correspondingly, for any $b \in B$, the condition $f(b)=0$ is fulfilled), where

$$
H(x)=\left\{\begin{array}{l}
1, \quad x>0,  \tag{1.2}\\
1 / 2, \quad x=0, \\
0, \quad x<0
\end{array}\right.
$$

is the Heaviside function and $(\cdot, \cdot)$ denotes the scalar product in $R^{n}$. Then decision rule (1.1) is called correct over sets $A$ and $B$. It is easy to see that rule $f$ gives 1 for vector $x \in R^{n}$ if

$$
\begin{equation*}
\sum_{i: H\left(l_{i}(x)\right)=1} w_{i}>\sum_{i: H\left(l_{i}(x)\right)=0} w_{i} \tag{1.3}
\end{equation*}
$$

and yields 0 when the reverse strict inequality holds, where $l_{i}(\cdot)=\left(d_{i}, \cdot\right)-\alpha_{i}, i=1, \ldots, k$.

The notion of separating committee of hyperplanes (linear functions) is closely related to correct decision rules (1.1).

[^0]Definition 1.1 [1]. A set $K=\left\{\left(l_{i}, w_{i}\right)\right\}_{i=1}^{k}$, of pairs is called a committee of linear functions which discriminates between (separates) two subsets $A$ and $B$ of $R^{n}$ if inequalities

$$
\begin{align*}
& \sum_{i: l_{i}(x)>0} w_{i}>q / 2, \quad \forall x \in A,  \tag{1.4}\\
& \sum_{i: l_{i}(x)<0} w_{i}>q / 2, \quad \forall x \in B
\end{align*}
$$

are satisfied where $w_{i} \in Z_{+}, i=1, \ldots, k, q=\sum_{i=1}^{k} w_{i}, Z_{+}$ denotes a set of positive integers. In addition, $q$ is called the number of elements of set $K$. Functions $l_{i}$ of the committee are called elements of $K$, whereas $w_{i}$ are called the weights (or multiplicities) of these elements.

The separating committee concept represents a simple generalization for a hyperplane that discriminates between two subsets. Furthermore, a committee $K=\left\{\left(l_{i}, w_{i}\right)\right\}_{i=1}^{k}$ of linear functions corresponds to a specific correct decision rule (1.1) such that the following inequalities hold true:

$$
\begin{align*}
& \sum_{i: H\left(l_{i}(x)\right)=1} w_{i}>q / 2, \quad \forall x \in A,  \tag{1.5}\\
& \sum_{i: H\left(l_{i}(x)\right)=0} w_{i}>q / 2, \quad \forall x \in B .
\end{align*}
$$

It is obvious that (1.5) is stronger than the correctness condition.


Figure. $(4,3,5)$-committee of five functions which discriminates between gray and black points. Its functions are depicted by their level sets $l(x)>0$. At every gray point at least four functions are positive, whereas for each black point at most three functions are nonnegative.

Theorem 1.1 [1]. A committee exists that separates two finite subsets $A$ and $B$ of $R^{n}$ iff $A \cap B=\varnothing$ where its number of elements does not exceed $|A \cup B|$.

Corollary [2]. The VC dimension for class of decision rules (1.1) is infinite.

It is also shown [2] that if $k \leq k_{0}$, then the VC dimension is $O\left(k_{0} n\right)$, where $k_{0}$ denotes some fixed positive integer.

The following problem is investigated.
Problem. What are the conditions for possibly infinite subsets $A$ and $B$ of $R^{n}$ under which a committee exists which discriminates between them?

Theorem 1.2 [3]. A committee exists separating two closed subsets $A$ and $B$ of $R^{n}$ iff $A \cap B=\varnothing$ and at least one of these subsets has a finite upper bound; as well one of the two has a finite lower bound.

Below, a separating ( $s, t, q$ )-committee concept is introduced (Def. 2.1), which covers separating committee notion (Def. 1.1) as a special case. Based on it a new technique is applied to give proofs for sufficient conditions under which two closed subsets $A$ and $B$ of $R^{n}$ with $A \cap B=\varnothing$ are separable by a committee.

## DEFINITION OF SEPARATING $(s, t, q)$-COMMITTEE

Let $A$ and $B$ be subsets of $R^{n}, s$ and $t$ be positive integers with $s>t$.

Definition 2.1 A set $K=\left\{\left(l_{i}, w_{i}\right)\right\}_{i=1}^{k}$ of pairs is called an $(s, t, q)$-committee of linear functions that
discriminates between two subsets $A$ and $B$ if the following inequalities hold true:

$$
\begin{align*}
& \sum_{i: l_{i}(x)>0} w_{i} \geq s, \quad \forall x \in A,  \tag{2.1}\\
& \sum_{i: l_{i}(x) \geq 0} w_{i} \leq t, \quad \forall x \in B,
\end{align*}
$$

where $l_{i}(\cdot)=\left(d_{i}, \cdot\right)-\alpha_{i}, d_{i} \in R^{n}, \alpha_{i} \in R, w_{i} \in Z_{+}$, $i=1, \ldots, k, q=\sum_{i=1}^{k} w_{i}$.

An example of a $(4,3,5)$-committee is shown in the figure. Obviously, the ( $s, t, q$ )-committee defines some piecewise-linear surface which separates subsets $A$ and $B$. It also corresponds to a decision rule of the form

$$
\begin{equation*}
f(\cdot)=H\left[\sum_{i=1}^{k} w_{i} H\left(l_{i}(\cdot)\right)-\frac{s+t}{2}\right] \tag{2.2}
\end{equation*}
$$

which is correct over sets $A$ and $B$. It is easy to show that the $(q, q-1, q)$-committee outlines the surface of a convex polyhedron $M$ containing set $A$ inside and set $B$ outside $R^{n / M}$. Furthermore, we obviously find that the ( $s, t, q$ )-committee becomes a committee for $s>q / 2>t$.

Suppose that set $A$ can be separated by a $(t+1, t$, $q$ )-committee from set $B$. Conversely, if $B$ is separable from $A$ by a surface of the same shape, then a ( $q-t$, $q-1-t, q)$-committee exists that separates $A$ and $B$.

The notions of a committee and the ( $s, t, q$ )-committee are closely related. Consider a set $K=$ $\left\{\left(l_{i}, w_{i}\right)\right\}_{i=1}^{k}$ of pairs. Let us find out what the conditions are under which this set can be augmented to some committee that separates $A$ and $B$ by adding one of two functions $l_{T}(\cdot) \equiv(0, \cdot)+1$ or $l_{F}(\cdot) \equiv(0, \cdot)-1$ with some weight where 0 denotes zero vector in $R^{n}$.

Theorem 2.1. The set of pairs $K=\left\{\left(l_{i}, w_{i}\right)\right\}_{i=1}^{k}$ can be transformed to a committee that discriminates between sets $A$ and $B$ in $R^{n}$ by adding one of two functions $l_{T}(\cdot) \equiv(0, \cdot)+1$ or $l_{F}(\cdot) \equiv(0, \cdot)-1$ iff $K$ is $a(s, t, q)$ committee that separates $A$ and $B$ for some positive integers $s$ and $t$ with $s>t$.

Proof. In the case when set $K$ transforms to a committee $\bar{K}$ by adding pair $\left(l_{T}, w_{k+1}\right)$, we have the following inequalities according to Def. 1.1:

$$
\begin{gather*}
\sum_{i \neq k+1, l_{i}(x)>0} w_{i}+w_{k+1}>p / 2, \quad x \in A  \tag{2.3}\\
\sum_{i \neq k+1, l_{i}(x)<0} w_{i}>p / 2, \quad x \in B
\end{gather*}
$$

where $p=\sum_{i=1}^{k+1} w_{i}$. It can be assumed that $p$ is odd (a committee whose number of elements is even can be reduced to a committee by decrementing weight $w_{i}$ of one of its functions $l_{i}$ ). Set $s=\lceil p / 2\rceil-w_{k+1}$ and $t=\lfloor p / 2\rfloor-w_{k+1}$, where $\lfloor x\rfloor$ and $\lceil x\rceil$ denote rounding to the closest integer, which is less than or more than real $x$, respectively. In view of $w_{i} \in Z_{+}$for every $i=1, \ldots, k+1$ and keeping in mind that $p$ is odd, we obtain

$$
\begin{gather*}
\sum_{i \neq k+1, l_{i}(x)>0} w_{i} \geq s, \quad x \in A  \tag{2.4}\\
\sum_{i \neq k+1, l_{i}(x) \geq 0} w_{i} \leq t, \quad x \in B
\end{gather*}
$$

If $K$ transforms to a committee $\bar{K}$ by adding pair $\left(l_{F}, w_{k+1}\right)$, the same path can be followed by setting $s=\lceil p / 2\rceil$ and $t=\lfloor p / 2\rfloor$.

$$
\text { Conversely, let } q=\sum_{i=1}^{k} w_{i} . \text { When } t<q / 2<s \text {, set } K \text { is }
$$ a committee that separates $A$ and $B$. Therefore, adding any two functions $l_{T}$ or $l_{F}$ with $w_{k+1}=0$ gives the committee $\bar{K}$. Now assume that $q / 2 \notin(t, s)$. Consider the case $q=2 h$ for some positive integer $h$. If $t \geq h$, we add the function $l_{F}$ to $K$ with $w_{k+1}=2(t-h)+1$. For the set $\bar{K}$ thus obtained we have $\sum_{i=1}^{k+1} w_{i}=2 t+1$. In view of $s>t$ and the inequalities

$$
\begin{gather*}
\sum_{i: l_{i}(x)>0} w_{i} \geq s \geq t+1, \quad x \in A  \tag{2.5}\\
\sum_{i: l_{i}(x) \geq 0} w_{i} \leq t, \quad x \in B
\end{gather*}
$$

we find that $\bar{K}$ is a committee. However, if $h>t$ then $h \geq s$. In this case let us add function $l_{T}$ to $K$ with $w_{k+1}=2(h-s)+1$. For the resulting set of pairs we have $\sum_{i=1}^{k+1} w_{i}=2(2 h-s)+1$ and
$\sum_{i: l_{i}(x)>0} w_{i} \geq s+2(h-s)+1=2 h-s+1, \quad x \in A$,

$$
\begin{equation*}
\sum_{i: l_{i}(x) \geq 0} w_{i} \leq t+2(h-s)+1 \leq 2 h-s, \quad x \in B \tag{2.6}
\end{equation*}
$$

where summation is performed over all $i$ from 1 to $k+1$.

Now consider the case $q=2 h-1$. When $h>s$, we add function $l_{T}$ to $K$ with $w_{k+1}=2(h-s)$. For the set of pairs thus augmented we find that $\sum_{i=1}^{k+1} w_{i}=2(2 h-s)-1$ and

$$
\begin{equation*}
\sum_{i: l_{i}(x)>0} w_{i} \geq s+2(h-s)=2 h-s, \quad x \in A \tag{2.7}
\end{equation*}
$$

$$
\sum_{i: l_{i}(x) \geq 0} w_{i} \leq t+2(h-s) \leq 2 h-s-1, \quad x \in B
$$

In the case $h \leq s$, the inequality $h \leq t$ holds. Let us add function $l_{F}$ to $K$ with $w_{k+1}=2(t-h+1)$ and follow the same path. We have $\sum_{i=1}^{k+1} w_{i}=2 t+1$ and

$$
\begin{equation*}
\sum_{i: l_{i}(x)>0} w_{i} \geq s \geq t+1, \quad x \in A \tag{2.8}
\end{equation*}
$$

$$
\sum_{i: l_{i}(x) \geq 0} w_{i} \leq t, \quad x \in B
$$

The theorem is proved.

## SUFFICIENT CONDITIONS FOR EXISTENCE OF A COMMITTEE THAT DISCRIMINATES BETWEEN TWO INFINITE SUBSETS OF $R^{n}$

Let us introduce some auxiliary constructions and notations. At first we describe union operation for two finite sets of pairs. Let $K$ and $L$ be two finite sets of pairs whose elements (first components of pairs, see Def. 1.1) belong to an arbitrary set $X$. Let us define the set of pairs $K^{\prime}$ in the following way. Each element of $K$ but not of $L$ is added to $K^{\prime}$ with the weight this element has for set $K$. Analogously, each element of $L$ not belonging to $K$ is added to $K^{\prime}$ with the same multiplicity as the one for $L$. Finally, each element which belongs to both $K$ and $L$ with weights $p_{1}$ and $p_{2}$, respectively, is included in $K^{\prime}$ with multiplicity $p_{1}+p_{2}$. Denote $K \cup L=: K^{\prime}$. For three sets $K_{1}, K_{2}$, and $K_{3}$ set $K_{1} \cup K_{2} \cup K_{3}:=\left(K_{1} \cup K_{2}\right) \cup K_{3}$. The union of four and more sets is defined in the same way.

In the sequel int $M$ denotes the interior of set $M$, whereas set cl $M$ gives closure of $M$ and bd $M$ is its border. For simplicity we identify linear function $l$ with its level set (half-space) $P=\left\{x \in R^{n}: l(x)>0\right\}$, whereas separating committee of linear functions is the same as the set of pairs of the form (half-space, its weight). If $l(x) \equiv \alpha \in R$, the corresponding half-space $P$ is the empty set for $\alpha \leq 0$ and coincides with the whole space for $\alpha>0$. Also we say that open half-space $P$ votes for point $a \in A$ if $a \in P$ and votes for $b \in B$ if $b \notin \mathrm{cl} P$.

If $P=\varnothing$, then $P$ votes for each point of $B$ (for set $B$ ) and against set $A$. In the opposite case, $P=R^{n}$ halfspace $P$ votes for set $A$ and against set $B$. It is easy to see that set of pairs $\left\{\left(l_{i}, w_{i}\right)\right\}_{i=1}^{k}$ is a committee that separates $A$ and $B$ iff for each point of $A \cup B$ a majority of half-spaces votes for in the corresponding set of pairs $\left\{\left(P_{i}, w_{i}\right)\right\}_{i=1}^{k}$, where $P_{i}=\left\{x \in R^{n}: l_{i}(x)>0\right\}, i=$ $1, \ldots, k$.

The following theorem generalizes theorem 1.1 in the case of infinite sets $A$ and $B$.

Theorem 3.1. If $A$ and $B$ are closed subsets of $R^{n}$ with $A \cap B=\varnothing$ such that one of them is bounded and has finite number of limiting points, then a committee exists that separates $A$ and $B$.

Proof. Let $A$ and $B$ be two closed subsets of $R^{n}$ with $A \cap B=\varnothing$ such that $A$ is bounded set having finite number of limiting points. It is easy to see that $A$ is countable or finite. As $A$ and $B$ are closed sets, $A$ is bounded and $A \cap B=\varnothing$, there exists such $\rho>0$ that any ball of radius $\rho$ centered at arbitrary point of $A$ does not contain points of $B$.

Let us give the following procedure. Let $A^{\prime}$ be an arbitrary finite subset of $A$ and $a \in A^{\prime}$ be some vertex of the convex hull conv $A^{\prime}$. Consider an arbitrary $n$ dimensional simplex $S$ containing convex hull conv $A^{\prime}$ which has point $a$ as one of its vertices. Get the ( $n-1$ )dimensional face of $S$ which is opposite to $a$ and consider hyperplane $H$ parallel to that face which cuts off an $n$-dimensional simplex from $S$ that is contained in the ball centered at $a$ of radius $\rho$.

Simplex $S$ is the intersection of some set of $n+1$ closed half-spaces. Let $P$ be the half-space containing point $a$ and whose border is hyperplane $H$. Let us shift each of these $n+1$ half-spaces bounding $S$ in parallel and denote by $T$ the simplex thus obtained. We perform shifting in such a way that $S \subset \operatorname{int} T$ and $A \cap$ $\mathrm{bd} T=\varnothing$. This last condition holds because $A$ is countable or finite. Moreover, we shift the half-space $P$ in parallel in such a way that the border of the shifted half-space starts to nip some $n$-dimensional simplex $T_{1}$ from simplex $T$ with $a \in \operatorname{int} T_{1}$ and $T_{1} \cap B=\varnothing$.

Simplices $T_{1}$ and $T$ have a common vertex, which we denote by $c_{1}$. Let $c_{2}, \ldots, c_{n+1}$ be the other vertices of $T$. For each $s=2, \ldots, n+1$ consider the cone $K_{s}$ bounded by $n$ different hyperplanes each of which passes through some ( $n-1$ )-dimensional face of $T$ containing point $c_{s}$ with $K_{s} \cap T=\left\{c_{s}\right\}$. Get the ( $n-1$ )dimensional face of $T$ opposite to $c_{s}$. Using a hyperplane parallel to that face, cut off some simplex $T_{s}$ from simplex $T$ such that $T_{s} \cap A=\varnothing$. Such a construction is possible in view of $c_{s} \notin A$. The procedure is finished.

This procedure is used for set $A^{\prime}$ from which elements are deleted consecutively. In three stages we get a committee that separates $A$ and $B$.

STAGE 1. Let $A_{0}$ be the set of limiting points of bounded set A which is finite due to the theorem. Set
$t_{0}=\left|A_{0}\right|$ and $A^{\prime}=A_{0}$. Consider a system of simplices $T$, $T_{1}, \ldots, T_{n+1}$ provided by the procedure applied for set $A^{\prime}$ and for an arbitrary vertex $a_{1}$ of convex hull conv $A^{\prime}$.
Let $V^{1}:=T$ and $V_{s}^{1}:=T_{s}, s=1, \ldots, n+1$. Setting $A^{\prime}:=$ $A^{\prime} \backslash\left\{a_{1}\right\}$ we apply the procedure for set $A^{\prime}$ and for an arbitrary vertex $a_{2}$ of convex hull conv $A^{\prime}$. As a result we have another system $T, T_{1}, \ldots, T_{n+1}$ of simplices. Let $V^{2}:=T$ and $V_{s}^{2}:=T_{s}, s=1, \ldots, n+1$ set $A^{\prime}:=A^{\prime} \backslash\left\{a_{2}\right\}$. We continue repeating the procedure until set $A^{\prime}$ becomes empty. Obviously, sequence $a_{1}, \ldots, a_{t_{0}}$ thus obtained coincides with set $A_{0}$. For each $r=1, \ldots, t_{0}$ consider an open neighborhood $U\left(a_{r}\right)$ of point $a_{r}$ which is contained in $V_{1}^{r} \cap \bigcap^{r-1} V^{r}$ as a subset. Due to $i=1$
the boundedness of $A$, the set $A_{1}=A \backslash \bigcup_{r=1}^{t_{0}} U\left(a_{r}\right)$ is finite.

In the case $A_{0}=\varnothing$, we set $A^{\prime}:=A_{1}=A$ and $p:=1$ going to stage 2 . Otherwise, for $A_{0} \neq \varnothing$ we apply the following simplex generation process. Set $p:=1$ and $A^{\prime}=A_{1} \cup \operatorname{ver} V^{1}$, where $\operatorname{ver} V^{1}$ is the vertex set for simplex $V^{1}$. When convex hull conv $A^{\prime}$ does not coincide with $V^{1}$, some point $a \in A_{1}$ will be a vertex of the hull. Obtain simplices $T, T_{1}, \ldots, T_{n+1}$ applying the procedure for the set $A^{\prime}$ and the point $a$. Set $a_{1}^{\prime}:=a, T^{1}:=$ $T, T_{s}^{1}:=T_{s}$, where $s=1, \ldots, n+1$. Then set $A^{\prime}:=$ $A^{\prime} \backslash\{a\}$ and $p:=2$. If the convex hull conv $A^{\prime}$ still does not equal to the simplex $V^{1}$ consider an arbitrary point $a \in A_{1}$ being a vertex of the hull. By applying the procedure for the set $A^{\prime}$ and the point $a$ we get another simplex series $T, T_{1}, \ldots, T_{n+1}$. Again set $a_{2}^{\prime}:=a, T^{2}:=$ $T, T_{s}^{2}:=T_{s}, s=1, \ldots, n+1$. Let $A^{\prime}:=A^{\prime} \backslash\{a\}$ and $p:=3$. While $\operatorname{conv} A^{\prime} \neq V^{1}$ we continue going in the same way.

Due to the fact that $A_{1} \backslash V^{1}$ is finite, we finally arrive at the case $\operatorname{conv} A^{\prime}=V^{1}$ for some $p=p_{1}$. Set $a_{p_{1}}^{\prime}:=a_{1}$, $T^{p_{1}}:=V^{1}, T_{s}^{p_{1}}:=V_{s}^{1}$, where $s=1, \ldots, n+1$. Let $p:=$ $p_{1}+1$. We now follow the same way of simplex generation for $r=2$. Specifically, let $A^{\prime}:=\left(A^{\prime} \backslash\right.$ ver $\left.^{r-1}\right) \cup$ ver $V^{r}$. If the convex hull conv $A^{\prime}$ does not coincide with $V^{r}$, let us get a vertex $a$ of the hull that is contained in $A_{1}$. By applying the procedure for set $A^{\prime}$ and point $a$, we obtain a system $T, T_{1}, \ldots, T_{n+1}$ of simplices. Then we set $a_{p}^{\prime}:=a, T^{p}:=T, T_{s}^{p}:=T_{s}, s=1, \ldots, n+1$ and let $A^{\prime}:=A^{\prime} \backslash\{a\}$ and $p:=p+1$. While conv $A^{\prime} \neq V^{\prime}$ we continue repeating this process. Again we come to the case where $\operatorname{conv} A^{\prime}=V^{r}$ for some $p=p_{r}$. Then let $a_{p_{r}}^{\prime}:=a_{r}$,

$$
T^{p_{r}}:=V^{r}, T_{s}^{p_{r}}:=V_{s}^{r}, s=1, \ldots, n+1 \text { and set } p:=p_{r+1} .
$$

The whole process works for $r=3,4, \ldots, t_{0}$. At the end we delete from $A^{\prime}$ all vertices of simplex $V^{t_{0}}$. It is easy to see that $A^{\prime}=A_{1} \cap \bigcap_{i=1}^{t_{0}} V^{r}$.

STAGE 2. In the case $A^{\prime} \neq \varnothing$ we apply the procedure for set $A^{\prime}$ and for an arbitrary vertex of its convex hull. Having provided the system of simplices $T$, $T_{1}, \ldots, T_{n+1}$, we set $a_{p}^{\prime}:=a, T^{p}:=T, T_{s}^{p}:=T_{s}, s=$ $1, \ldots, n+1$. Also let $A^{\prime}:=A^{\prime} \backslash\{a\}$ and $p:=p+1$. Finally, while set $A^{\prime}$ is nonempty we continue doing the same.

STAGE 3. At the end of stage 2, we have two families $\left\{T^{k}\right\}$ and $\left\{T_{s}^{k}\right\}$ of simplices where $s=1, \ldots, n+1$ and $k=1, \ldots, t, t=\left|A_{0}\right|+\left|A_{1}\right|$. For each $k, 1 \leq k \leq t$, define a series of open half-spaces $\left\{P_{i}^{k}\right\}_{i=1}^{2 n+2}$ by the conditions int $T^{k}=\bigcap_{i=1}^{n+1} P_{i}^{k} \operatorname{int} T_{1}^{k}=\bigcap_{i=2}^{n+2} P_{i}^{k}$ and $\operatorname{int} T_{s}^{k}=Q_{n+1+s}^{k} \cap \bigcap^{n+1} Q_{i}^{k}$, where $2 \leq s \leq n+1$ and $i=1, i \neq s$
$Q_{i}^{k}$ is the open half-space distinct from $P_{i}^{k}$, which has a common boundary with $P_{i}^{k}$. Equip set $L_{k}$ of pairs with these half-spaces taken with some multiplicities. Each of the half-spaces $\left\{P_{i}^{k}\right\}_{i=1}^{n+1}$ will have weight $n \cdot n^{2(t-k)}$, whereas each of the half-spaces $\left\{P_{i}^{k}\right\}_{i=n+2}^{2 n+2}$, the weight $n^{2(t-k)}$. Let $K_{0}=\left\{\left(P_{0}, w_{0}\right)\right\}$, where $P_{0}=\left\{x \in R^{n}:(0, x)>1\right\}$ and $w_{0}=n^{2 t}$. Set $K=$ $K_{0} \cup L_{1} \cup \ldots \cup L_{t}$, where symbol $\cup$ denotes union operation. Stage 3 is finished.

Let us show that $K$ is a committee. Consider the case where $n \neq 1$. Since the number of elements for the set $L_{k}$ is equal to $(n+1)^{2} n^{2(t-k)}, k=1, \ldots, t$, the number of elements for $K$ is equal to

$$
\begin{gather*}
(n+1)^{2}\left(n^{2(t-1)}+n^{2(t-2)}+\ldots+1\right)+n^{2 t} \\
=2 n^{2 t}-1+\frac{2}{n-1}\left(n^{2 t}-1\right) \tag{3.1}
\end{gather*}
$$

Let us count the number of elements of $L_{k}, k=1, \ldots, t$ which vote for some $a \in A$. Due to the procedure, two situations are possible for each point $a \in A: a$ is in the interior of simplex $T^{k}$; otherwise it lies in its open exterior. If $a \in \operatorname{int} T^{k}$, the half-spaces $\left\{P_{i}^{k}\right\}_{i=1}^{n+1}$ vote for point $a$ by their multiplicities $n \cdot n^{2(t-k)}$, totaling $(n+1) n \cdot n^{2(t-k)}$ votes. Moreover, if $a \in \operatorname{int} T_{1}^{k}$, halfspace $P_{n+2}^{k}$ votes for $a$ by its weight $n^{2(t-k)}$ and each of the half-spaces $\left\{P_{i}^{k}\right\}_{i=1}^{n+1}$, by their multiplicities $n \cdot n^{2(t-k)}$, which amounts to $((n+1) n+1) n^{2(t-k)}$
votes. Two cases are possible for $a \notin T^{k}$. The first case takes place when $a \in P_{i_{1}}^{k} \cap P_{i_{2}}^{k}$ for some $i_{1}$ and $i_{2}, 1 \leq$ $i_{1}, i_{2} \leq n+1$. The second case is where $a \in$ $\bigcap^{n+1} \mathrm{cl}_{i}^{k}$, for some $i_{0}, 1 \leq i_{0} \leq n+1$. If the first case $i=1, i \neq i_{0}$ holds, there are at least $2 n \cdot n^{2(t-k)}$ votes for point $a$ in set $L_{k}$. In the second case, in view of $T_{s}^{k} \cap A=\varnothing$ for every $s=2, \ldots, n+1$ and taking inclusion $P_{n+2}^{k} \supset$ $\bigcap_{i}^{n+1} \operatorname{cl} Q_{i}^{k}$ into account, we find that half-space $P_{i_{0}}^{k}$ $i=2$
votes for point $a$ a by its weight $n \cdot n^{2(t-k)}$, while halfspace $P_{n+1+i_{0}}^{k}$ does the same by its multiplicity $n^{2(t-k)}$, which totals $(n+1) n^{2(t-k)}$ votes in $L_{k}$.

Let us count the number of elements of $K$ which vote for some point $a \in A$. Obviously, the finite sequence $a_{1}^{\prime}, \ldots, a_{t}^{\prime}$ of distinct points that forms at stages 1 and 2 coincides with set $A_{0} \cup A_{1}$. In view of equality $A=A_{1} \cup \bigcup\left(U\left(a^{\prime}\right) \cap A\right)$, we have either $a=$

$$
a^{\prime} \in A_{0}
$$

$a_{p}^{\prime}$ for some $p, 1 \leq p \leq t$ or $a \in U\left(a^{0}\right)$, where $a^{0} \in A_{0}$. Let us count the number of votes for the first case. Due to the generation procedure for simplices $\left\{T^{k}\right\}$ and $\left\{T_{s}^{k}\right\}$, point $a$ lies inside the intersection $T_{1}^{p} \cap \bigcap_{1<k<p} T^{k}$. Consequently, for $p \neq 1$ and $p \neq t$, the number of elements of $K$ which vote for $a$ is greater than or equal to

$$
\begin{gather*}
(n+1) n\left(n^{2(t-1)}+\ldots+n^{2(t-p+1)}\right) \\
+((n+1) n+1) n^{2(t-p)} \\
+(n+1)\left(n^{2(t-p-1)}+\ldots+1\right)=n^{2 t}-n^{2(t-p+1)} \\
+\frac{1}{n-1}\left(n^{2 t}-n^{2(t-p+1)}\right)+n^{2(t-p+1)}  \tag{3.2}\\
+\frac{1}{n-1} n^{2(t-p+1)}-\frac{1}{n-1} n^{2(t-p)} \\
+\frac{1}{n-1} n^{2(t-p)}-\frac{1}{n-1}=n^{2 t}+\frac{1}{n-1}\left(n^{2 t}-1\right)
\end{gather*}
$$

For $p=1$, this number is greater than or equal to

$$
\begin{gather*}
((n+1) n+1) n^{2(t-1)}+(n+1)\left(n^{2(t-2)}+\ldots+1\right) \\
=n^{2 t}+\frac{1}{n-1}\left(n^{2 t}-1\right) \tag{3.3}
\end{gather*}
$$

Analogously, for $p=t$ the number is at least as great as

$$
\begin{gather*}
(n+1) n\left(n^{2(t-1)}+\ldots+n^{2}\right)+((n+1) n+1) \\
=n^{2 t}+\frac{1}{n-1}\left(n^{2 t}-1\right) \tag{3.4}
\end{gather*}
$$

Now consider the case $a \in U\left(a^{0}\right)$, where $a^{0}$ is some point of set $A_{0}$. Since $a^{0}=a_{p}^{\prime}$ for some $p, 1 \leq p \leq t$, point $a$ lies inside intersection $T_{1}^{p} \cap \bigcap T^{k}$ by the con$1 \leq k<p$ struction of neighborhood $U\left(a^{0}\right)$ and series of simplices $\left\{T^{k}\right\}$ and $\left\{T_{s}^{k}\right\}$. As a consequence, there are at least $n^{2 t}+\frac{1}{n-1}\left(n^{2 t}-1\right)$ votes in $K$ for point $a$.

For every point $b \in B$, let us now count the number of elements of $L_{k}, k=1, \ldots, t$, which vote for $b$. If $b \in T^{k}$, we have $b \notin T_{1}^{k}$ according to the construction of simplex $T_{1}^{k}$. For this point, each of the half-spaces $\left\{P_{i}^{k}\right\}_{i=n+2}^{2 n+2}$ votes by its weight $n^{2(t-k)}$, which overall amounts to $(n+1) n^{2(t-k)}$ votes. In the case of $b \notin T^{k}$, some half-space $P_{i_{0}}^{k}, 1 \leq i_{0 \leq n+1}$, votes for $b$ by its multiplicity $n \cdot n^{2(t-k)}$ and so does half-space $P_{n+1+i_{0}}^{k}$ by its weight $n^{2(t-k)}$, whose boundary is parallel to that for $P_{i_{0}}^{k}$. It sums up to give at least $(n+1) n^{2(t-k)}$ votes for $b$ in $L_{k}$. Due to the fact that $P_{0}$ votes for the $B$ by its multiplicity $n^{2 t}$, the number of elements of $K$ which vote for point $b$ is at least as much as $(n+1)\left(n^{2(t-1)}+\right.$ $\ldots+1)+n^{2 t}=n^{2 t}+\frac{1}{n-1}\left(n^{2 t}-1\right)$, so $K$ is a committee.

For $n=1$ it is easy to count that the number of elements of $K$ is equal to $4 t+1$, while the number of elements voting for an arbitrary point of $A \cup B$ is greater than or equal to $2 t+1$. The theorem is proved.

Remark. Using more general notion of an $(s, t, q)$ committee yields a simpler proof for the case where set $A$ is finite.

The boundedness condition imposed on one of two sets being separated is essential.

Example. There is no committee which separates sets $A=\{2 k\}_{k=1}^{\infty}$ and $B=\{2 k-1\}_{k=1}^{\infty}$.

In contrast, if such a committee exists, there is a linear function in $K$ having a positive weight that takes positive value for $2 k$ and gives a negative value for $2 k-$ 1 , where $k$ is an arbitrary positive integer. Due to the fact that these functions are different for distinct $k$ and using the finiteness of the committee, we find that a committee that separates these two sets does not exist.

Let us give the classical result on the external approximation of solid convex compact by a convex
polyhedron to arbitrary accuracy (see, e.g., [5]). We call

$$
\begin{gather*}
\delta\left(C_{1}, C_{2}\right)=\max \left[\sup \left\{\rho\left(x, C_{2}\right): x \in C_{1}\right\},\right.  \tag{3.5}\\
\left.\sup \left\{\rho\left(x, C_{1}\right): x_{2} \in C_{2}\right\}\right]
\end{gather*}
$$

the Hausdorff metric between two convex compact subsets $C_{1}$ and $C_{2}$ of $R^{n}$ having a nonempty interior (which are called convex bodies), where $\rho(x, C):=$ $\inf \{|x-y|: y \in C\}$ and $|\cdot|$ denotes the Euclidean norm. For a given convex body $C$, we consider convex hulls of finite sets with at most $m$ faces (facets having the maximal dimension), which contain set $C$ and touch its boundary where $m$ is given positive integer. We denote by $P_{m}^{c}(C)$ the set of all convex hulls of this form and set $\delta\left(C, P_{m}^{c}(C)\right)=\inf \left\{\delta(C, D): D \in P_{m}^{c}(C)\right\}$.

Theorem 3.2 [5]. The following equality holds true: $\lim _{m \rightarrow \infty} \delta\left(C, P_{m}^{c}(C)\right)=0$.

The following theorem is closely related to the classical result on the separability of two convex sets by a hyperplane.

Theorem 3.3. If $A$ and $B$ are closed subsets of $R^{n}$ with an empty intersection where $A$ is a convex body, then $A$ and $B$ are separable by a committee.

Proof. Since $A$ is compact, $B$ is closed and $A \cap B=$ $\varnothing$ we have

$$
\begin{equation*}
\rho(A, B):=\inf \{|x-y|: x \in A, y \in B\}=\varepsilon_{0}>0 \tag{3.6}
\end{equation*}
$$

Set $A(\varepsilon)=\bigcup_{x \in A} O_{x}(\varepsilon)$ is a compact body, where $O_{x}(\varepsilon)$
is an $n$-dimensional ball centered at point $x \in R^{n}$ of radius $\varepsilon$. Set $A_{0}=A\left(\varepsilon_{0} / 4\right)$. Then $\rho\left(A_{0}, B\right)>\varepsilon_{0} / 2$. Choose a positive integer $m$ large enough to have $\delta\left(A_{0}\right.$, $\left.P_{m}^{c}\left(A_{0}\right)\right)<\varepsilon_{0} / 4$. Therefore, there exists $M \in P_{m}^{c}\left(A_{0}\right)$ such that $A_{0} \subseteq M$ and $M \cap B=\varnothing$ so that $A \subseteq \operatorname{int} M$. Because $M$ coincides with the intersection of a finite number (say, $t \leq m$ ) of closed half-spaces, there exists a ( $t, t-1, t$ )-committee that separates $A$ and $B$. Then, according to theorem 2.1, there exists a committee that separates them. The theorem is proved.

## CONCLUSIONS

A new concept of the $(s, t, q)$-committee decision rule is introduced which includes the committee decision rule as a special case. A series of sufficient conditions for two subsets $A$ and $B$ of $R^{n}$ is considered under which there exists a correct decision rule where $A$ and $B$ are not finite in general. These results generalize Vl.D.Mazurov's famous criterion on the separability of two finite subsets of $R^{n}$ having an empty intersection.

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[^0]:    ${ }^{1}$ The article was translated by the authors.

